

Stat 6871 Homework 1

1/9

$$\begin{aligned} \textcircled{1} \quad \gamma_X(r, s) &= \text{Cov}(X_r, X_s) = E[(X_r - \mu_X(r))(X_s - \mu_X(s))] \\ &= E[X_r X_s - X_r \mu_X(s) - \mu_X(r) X_s + \mu_X(r) \mu_X(s)] \\ &= E[X_r X_s] - E[X_r] \mu_X(s) - \mu_X(r) E[X_s] \\ &\quad + \mu_X(r) \mu_X(s) \\ &= E[X_r X_s] - \mu_X(r) \mu_X(s) - \mu_X(r) \mu_X(s) \\ &\quad + \mu_X(r) \mu_X(s) \\ &= E[X_r X_s] - \mu_X(r) \mu_X(s) \quad \square \end{aligned}$$

$\textcircled{2}$  Assume  $X_t$  is a stationary process and  
 $X_t = \phi X_{t-1} + z_t$ ,  $t = 0, \pm 1, \dots$  where  $z_t$  is iid  
 $WN(0, \sigma^2)$ ,  $|\phi| < 1$  and  $z_t$  is uncorrelated  
with  $X_s$ ,  $s < t$ .

$$\begin{aligned} \underline{\text{mean}}: \mu_X &= E[X_t] = E[\phi X_{t-1} + z_t] = \phi E[X_{t-1}] + E[z_t] \\ &= \phi \mu_X + 0 \quad \text{since } X_t \text{ is stationary} \\ \Rightarrow \mu_X &= \phi \mu_X \Rightarrow \mu_X = 0 \quad \text{since } |\phi| < 1 \end{aligned}$$

ACVF:  $\gamma_X(h) = \text{Cov}(X_{t+h}, X_t) = E[X_{t+h} X_t]$

$$= E[(\phi X_{t+h-1} + z_{t+h}) X_t]$$

$$= E[\phi X_{t+h-1} X_t] + E[z_{t+h} X_t]$$

$$= \phi E[X_{t+h-1} X_t] + E[z_{t+h}] E[X_t]$$

$$= \phi \gamma_X(h-1) + 0 \quad \text{since } z_t \stackrel{i}{\perp} X_s$$

are uncorrelated  
t > s.

So  $\gamma_X(h) = \phi \gamma_X(h-1)$

$$\Rightarrow \gamma_X(h) = \phi^h \gamma_X(0)$$

Note that  $\gamma_X(h) = \gamma(-h)$  . so

$$\gamma_X(h) = \phi^{|h|} \gamma_X(0) \quad h=0, \pm 1, \pm 2, \dots$$

Calculate  $\gamma_X(0)$

$$\gamma_X(0) = \text{Cov}(X_t, X_t) = \text{Cov}(X_t, \phi X_{t-1} + z_t)$$

$$= \phi \text{Cov}(X_t, X_{t-1}) + \text{Cov}(X_t, z_t)$$

$$= \phi \gamma_X(1) + \text{Cov}(\phi X_{t-1} + z_t, z_t)$$

$$= \phi \gamma_X(1) + \phi \text{Cov}(X_{t-1}, z_t)$$

$$+ \text{Cov}(z_t, z_t)$$

note  $\text{Cov}(X_{t-1}, z_t) = 0$  since  $t-1 < t$ .

$$\therefore \gamma_X(0) = \phi \gamma_X(1) + \sigma^2$$

$$\Rightarrow \gamma_X(0) = \phi [\phi \gamma_X(0)] + \sigma^2$$

$$\gamma_X(0) = \phi^2 \gamma_X(0) + \sigma^2$$

solving  $\gamma_X(0) = \frac{\sigma^2}{1-\phi^2}$

$$\therefore \gamma_X(h) = \phi^{|h|} \frac{\sigma^2}{1-\phi^2} \quad h=0, \pm 1, \dots$$

and  $\rho_X(h) = \frac{\gamma_X(h)}{\gamma_X(0)} = \phi^{|h|} \quad h=0, \pm 1, \dots$

③  $X_t = z_{t-1} + 2z_t + z_{t+1} \quad z_t \stackrel{iid}{\sim} N(0, \sigma^2)$

mean:  $E[X_t] = E[z_{t-1} + 2z_t + z_{t+1}]$   
 $= E[z_{t-1}] + 2E[z_t] + E[z_{t+1}]$   
 $= 0$

ACVF:  $\gamma_X(h) = \text{Cov}(X_{t+h}, X_t) = E[X_{t+h} X_t]$   
 $= E[(z_{t+h-1} + 2z_{t+h} + z_{t+h+1})(z_{t-1} + 2z_t + z_{t+1})]$

$$= E \left[ z_{t+h-1} z_{t-1} + 2z_{t+h-1} z_t + z_{t+h-1} z_{t+1} \right. \\ \left. + 2z_{t+h} z_{t-1} + 4z_{t+h} z_t + 2z_{t+h} z_{t+1} \right. \\ \left. + z_{t+h+1} z_{t-1} + 2z_{t+h+1} z_t + z_{t+h+1} z_{t+1} \right]$$

$$h=0 \quad \gamma_x(0) = E \left[ z_{t-1}^2 + 4z_t^2 + z_{t+1}^2 \right] \\ = \sigma^2 + 4\sigma^2 + \sigma^2 = 6\sigma^2$$

$$h=1 \quad \gamma_x(1) = E \left[ 2z_t^2 + 2z_{t+1}^2 \right] = 4\sigma^2$$

$$h=-1 \quad \gamma_x(-1) = E \left[ 2z_{t-1}^2 + 2z_t^2 \right] = 4\sigma^2$$

$$h=2 \quad \gamma_x(2) = E \left[ z_{t+1}^2 \right] = \sigma^2$$

$$h=-2 \quad \gamma_x(-2) = E \left[ z_{t-1}^2 \right] = \sigma^2$$

$$|h| \geq 3 \quad \gamma_x(h) = 0$$

$$\therefore \gamma_x(h) = \begin{cases} 6\sigma^2 & h=0 \\ 4\sigma^2 & h=\pm 1 \\ \sigma^2 & h=\pm 2 \\ 0 & |h| \geq 3 \end{cases}$$

$$\therefore \rho_x(h) = \frac{\gamma_x(h)}{\gamma_x(0)} = \begin{cases} 1 & h=0 \\ \frac{2}{3} & h=\pm 1 \\ \frac{1}{6} & h=\pm 2 \\ 0 & |h| \geq 3 \end{cases}$$

④ Problem 1.7  $X_t$  and  $Y_t$  are uncorrelated

Show  $X_t + Y_t$  is stationary

$$E[X_t + Y_t] = E[X_t] + E[Y_t] = \mu_x + \mu_y.$$

$$\gamma_{X+Y}(h) = E\left[ \left( X_{t+h} + Y_{t+h} - E[X_{t+h} + Y_{t+h}] \right) \left( X_t + Y_t - E[X_t + Y_t] \right) \right].$$

$$= E\left[ \left( (X_{t+h} + Y_{t+h}) - (\mu_x + \mu_y) \right) \left( (X_t + Y_t) - (\mu_x + \mu_y) \right) \right].$$

$$= E\left[ (X_{t+h} + Y_{t+h})(X_t + Y_t) - (\mu_x + \mu_y)(\mu_x + \mu_y) \right]$$

$$= E\left[ X_{t+h} X_t + X_{t+h} Y_t - X_t Y_{t+h} + Y_{t+h} Y_t \right] - (\mu_x + \mu_y)^2$$

$$= E[X_{t+h} X_t] + E[X_{t+h} Y_t] + E[X_t Y_{t+h}] + E[Y_{t+h} Y_t] - (\mu_x + \mu_y)^2$$

$$\begin{aligned}
&= E[X_{t+h} X_t] - \mu_x^2 + E[Y_{t+h} Y_t] - \mu_y^2 \\
&= E[(X_{t+h} - \mu_x)(X_t - \mu_x)] \\
&\quad + E[(Y_{t+h} - \mu_y)(Y_t - \mu_y)] \\
&= \gamma_x(h) + \gamma_y(h).
\end{aligned}$$

$\therefore X_t + Y_t$  is stationary and

$$\gamma_{X+Y}(h) = \gamma_x(h) + \gamma_y(h).$$

⑤  $X_t \stackrel{iid}{\sim} (0, \sigma^2)$  random walk model  $S_t = \sum_{s=1}^t X_s$ .

$$\begin{aligned}
a) E[S_t] &= E\left[\sum_{s=1}^t X_s\right] = E[X_1 + X_2 + \dots + X_t] \\
&= E[X_1] + E[X_2] + \dots + E[X_t] \\
&= 0 + 0 + \dots + 0 = 0.
\end{aligned}$$

$$\begin{aligned}
\gamma_s(h) &= \text{Cov}(S_{t+h}, S_t) = E[S_{t+h} S_t] \\
&= E[(X_1 + X_2 + \dots + X_{t+h}) S_t] \\
&= E[X_1 S_t + X_2 S_t + \dots + X_{t+h} S_t]
\end{aligned}$$

$$= E\left[X_1 \sum_{s=1}^t X_s\right] + E\left[X_2 \sum_{s=1}^t X_s\right] + \dots \\ + E\left[X_{t+h} \sum_{s=1}^t X_s\right].$$

$$= E\left[X_1^2 + X_1 X_2 + \dots + X_1 X_t\right] \\ + E\left[X_2^2\right] + \dots + E\left[X_t^2\right] \\ + 0 + \dots + 0$$

note  $E[X_1 X_2] = 0$   
since  $X_t \sim i.i.d. (0, \sigma^2)$

$$= \underbrace{\sigma^2 + \dots + \sigma^2}_t + \underbrace{0 + \dots + 0}_h$$

$$= t\sigma^2 \quad \text{nonstationary, } \gamma_X(h) \text{ depends on } t.$$

b)  $S_t$  is nonstationary since  $\gamma_X(h) = t\sigma^2$ .

c) difference  $S_t$

$$\nabla S_t = S_t - S_{t-1} = \sum_{s=1}^t X_s - \sum_{s=1}^{t-1} X_s = X_t$$

$$E[\nabla S_t] = E[X_t] = 0$$

$$\gamma_{\nabla S}(h) = E[X_{t+h} X_t] = \begin{cases} \sigma^2 & h=0 \\ 0 & |h| \geq 1 \end{cases}$$

So  $\nabla S_t = X_t$  is stationary.

$$\textcircled{6} \quad X_t = \beta_0 + \beta_1 t + z_t \quad z_t \stackrel{iid}{\sim} (0, \sigma^2)$$

$$\begin{aligned} \text{a) } E[X_t] &= E[\beta_0 + \beta_1 t + z_t] = E[\beta_0 + \beta_1 t] + E[z_t] \\ &= \beta_0 + \beta_1 t. \end{aligned}$$

$X_t$  is nonstationary since  $E[X_t]$  depends on  $t$ .

$$\begin{aligned} \text{b) } \nabla X_t &= X_t - X_{t-1} = \beta_0 + \beta_1 t + z_t - (\beta_0 + \beta_1 (t-1) + z_{t-1}) \\ &= \cancel{\beta_0} + \beta_1 t + z_t - \cancel{\beta_0} - \beta_1 t + \beta_1 + z_t - z_{t-1} \\ &= \beta_1 + z_t - z_{t-1} \end{aligned}$$

$$\begin{aligned} E[\nabla X_t] &= E[\beta_1 + z_t - z_{t-1}] \\ &= \beta_1 + E[z_t] - E[z_{t-1}] = \beta_1 + \underbrace{0}_{=0} - \underbrace{0}_{=0} \\ &= \beta_1 \end{aligned}$$

$$\begin{aligned} \gamma_{\nabla X}(h) &= \text{Cov}(\nabla X_{t+h}, \nabla X_t) \\ &= E[(\nabla X_{t+h} - E[\nabla X_{t+h}])(\nabla X_t - E[\nabla X_t])] \\ &= E[(\beta_1 + z_{t+h} - z_{t+h-1} - \beta_1)(\beta_1 + z_t - z_{t-1} - \beta_1)] \end{aligned}$$



$$= E[(z_{t+h} - z_{t+h-1})(z_t - z_{t-1})]$$

$$= E[z_{t+h} z_t - z_{t+h} z_{t-1} - z_{t+h-1} z_t + z_{t+h-1} z_{t-1}]$$

$$\gamma_x(0) = E[z_t^2] + E[z_{t-1}^2] = 2\sigma^2$$

$$\gamma_x(1) = -E[z_t^2] = -\sigma^2$$

$$\gamma_x(-1) = -E[z_{t-1}^2] = -\sigma^2$$

$$\gamma_x(2) = 0 \quad \gamma_x(-2) = 0$$

$$\gamma_x(h) = \begin{cases} 2\sigma^2 & h=0 \\ -\sigma^2 & h=\pm 1 \\ 0 & |h| \geq 2 \end{cases}$$

$$\rho_x(h) = \begin{cases} 1 & h=0 \\ -\frac{1}{2} & h=\pm 1 \\ 0 & |h| \geq 2 \end{cases}$$