

**THE BASICS  
OF TALKING  
BAYESIAN STATISTICS**

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## Introduction

- Bayesian methods have become popular and their use continues to grow

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**A 236-year-old approach to statistics is making a comeback, as its ability to factor in hunches as well as hard data finds applications from pharmaceuticals to fisheries**

- Bayesian statisticians need to communicate with
  - policymakers and decisionmakers
  - researchers in other fields
  - classically trained statisticians
- Today: comments based on my experiences
  - what do Bayesian methods offer
  - some things that are hard to explain
  - illustrate via several examples
  - summary/conclusions

## Terminology

- Bayesian methods
  - treat all unknowns as random variables
  - condition on observed data
  - a.k.a. inverse probability
  - ‘Bayesian’ is a relatively recent term
- Non-Bayesian methods
  - frequentist? .... but that refers to an interpretation of probability or an approach for evaluating procedures
  - classical? .... but Bayes published first
  - traditional? .... but whose tradition!

## What do Bayesian methods have to offer

- They make explicit use of probability
- They allow “flexibility” in inference
- Developing/extending models is a natural process
- They provide a way to incorporate prior information
- Computational benefits

## **Ex. 1: linear models in animal breeding**

- Animal breeding research
  - estimate/predict genetic potential of animals for one or more trait
  - use information from each animal and its relatives
  - select the best animals for breeding
  - example today: flour beetles  
(Wright, Stern and Berger, JABES 2000)

## Ex. 1: linear models in animal breeding

- The model

$$Y = X\beta + Z_1u + Z_2c + e$$

- $Y$  = vector of  $n$  trait measurements
- $X$  = matrix of “fixed” effects (e.g., sex)
- $\beta$  = vector of  $p$  fixed effect coefficients
- $Z_1$  = incidence matrix for animal effects
- $u$  = vector of  $N$  animal random effects
- $Z_2$  = incidence matrix for family (env.) effects
- $c$  = vector of  $q$  family random effects
- $e$  = vector of random errors
- our example (a small problem):  
 $n = 324, N = 397, q = 54, p = 6$

## Ex. 1: linear models in animal breeding

$$Y = X\beta + Z_1u + Z_2c + e$$

- Distributional assumptions
  - $u \sim N(0, \sigma_a^2 A)$   
 $A$  is known  $N \times N$  relationship matrix
  - $c \sim N(0, \sigma_c^2 I)$
  - $e \sim N(0, \sigma_e^2 I)$
- Normality for  $u$  is usually justified by thinking of “infinitesimal” model
- Normality for  $e$  may be achieved by transformation
- Possible problems/opportunities
  - major genes
  - outliers (preferential treatments)

## Ex. 1: linear models in animal breeding

- Classical approach (REML/BLUP)
  - inference for variance components using restricted maximum likelihood (REML)
  - inference for random effects given variance components

\* solve Henderson's equations

\* equivalent to maximizing  $p(u, c, \beta | Y, \sigma^2)$

$$\begin{pmatrix} X'X & X'Z_1 & X'Z_2 \\ Z_1'X & Z_1'Z_1 + A^{-1} \frac{\sigma_e^2}{\sigma_a^2} & Z_1'Z_2 \\ Z_2'X & Z_2'Z_1 & Z_2'Z_2 + I_q \frac{\sigma_e^2}{\sigma_a^2} \end{pmatrix} \begin{pmatrix} \beta \\ u \\ c \end{pmatrix} = \begin{pmatrix} X'Y \\ Z_1'Y \\ Z_2'Y \end{pmatrix}$$

\* yields best linear unbiased predictions (BLUP)

\* may require solving large system of equations (can be thousands of rows)

## Ex. 1: linear models in animal breeding

- Bayesian approach
  - probability model
    - \*  $p(y|u, c, \beta, \sigma^2) = N(y|X\beta + Z_1u + Z_2c, \sigma_e^2 I_n)$
    - \*  $p(u|\sigma_a^2) = N(u|0, \sigma_a^2 A)$
    - \*  $p(c|\sigma_c^2) = N(c|0, \sigma_c^2 I_q)$
    - \*  $p(\beta) \propto 1$
    - \*  $p(\sigma_a^2, \sigma_c^2, \sigma_e^2) \propto 1/\sigma_e^2$
    - \* last two are noninformative(?) and improper prior distributions
  - Markov chain Monte Carlo sampling can be used to study posterior (Gibbs sampling is easy to implement for this model)

## Ex. 1: linear models in animal breeding

- Tribolium castaneum data (flour beetles)
  - $n = 324$  animals
    - \* one generation out of 16 in study
  - $N = 397$  animals (includes 73 ancestors)
  - $p = 6$  “fixed effects”  
(intercept, gender, date, interactions)
  - $q = 54$  environments
    - \* 6 beetles taken from each mating and raised in common environment

## Ex. 1: linear models in animal breeding

- Variance components

Parameter	Posterior distribution			Poster. mean	REML
	2.5%	50%	97.5%		
$\sigma_a^2$	757	6301	22919	7781	2253
$\sigma_c^2$	290	3881	11396	4371	4426
$\sigma_e^2$	30354	40834	50202	40682	43405
heritability	0.014	0.121	0.398	0.145	0.045

## **Ex. 1: linear models in animal breeding**

- Animal effects are of great interest
  - BLUP estimates are posterior means conditional on REML variance estimates
  - full Bayesian posterior means accommodate uncertainty about variance parameters
  - both are motivated by squared error loss
  - a key point is that other summaries of the posterior distn are possible

## Ex. 1: linear models in animal breeding

- What do we learn
  - flexible inferences (e.g., ranks)
  - incorporate prior information at some levels of the model (i.e., family structure) ... but not at others
  - computationally convenient
- What questions come up
  - defining optimal point estimates (post. mean, post. median, post. mode)
  - role of prior distributions for variances

## Ex. 2: estimation of soil texture quantiles

- Soil texture or composition variables (e.g., % clay) are important for land management
- Goal: estimate quantiles of distn of soil texture variables for 48 inch profile
- Data available
  - horizon = layer of soil
  - S = surface points (field measurements only on surface horizon, 6-12 in)
  - F = field points (field measurements on all horizons up to 48 in)
  - L = lab points (field and lab data on all horizons up to 48 in)
  - lots of missing data (e.g., lab measurements on S and F sites)
- Data are from National Cooperative Soil Survey (NCSS), a USDA/state agencies production
- Ph.D. thesis of P. J. Abbitt (ISU, 1999)

## Ex. 2: estimation of soil texture quantiles

- Calibration/imputation approach
  - calibration
    - \* linear model used to calibrate field and lab measurements
    - \* lab measurements modeled as a function of field measurements (and other variables) using sites with both types of data
    - \* “predict” lab measurements for sites in S/F
    - \* different models used for different types of soils

## Ex. 2: estimation of soil texture quantiles

- Calibration/imputation approach (cont'd)
  - imputation
    - \* after calibration have complete “lab” data except for sites in  $S$
    - \* next impute calibrated lab data for full profile for sites in  $S$
    - \* regression model to impute inch  $i$ 's data using inch 1's data as predictor
    - \* different models used for different types of soils
  - quantile function estimator
  - variance estimation via jackknife

## Ex. 2: estimation of soil texture quantiles

- Hierarchical probability model
  - normal linear model relates field measurements to lab measurements (similar to calibration step)
  - lab measurements model
    - \* normal distribution
    - \* site random effect
    - \* mean and variance differ by horizon type (A, B, C)
  - horizon profile is a Markov model (six states at any inch: continue A, start A, continue B, start B, continue C, start C)
- Bayesian inference via MCMC (priors are vague distns centered at values based on science)
- Quantile estimates derived from a mixture of normal (lab measurement) distns with mixture weights a function of the Markov model probs

## Ex. 2: estimation of soil texture quantiles

- Bayesian analysis vs calibration/imputation
  - computation is more difficult for the Bayesian approach
  - calibration approach is series of separate steps
  - more distributional assumptions for Bayesian approach (requires more model checking)
  - Bayesian approach does not rely on asymptotics
  - Bayesian approach provides flexible inference (more/better output)
  - as an example we consider:  
quantiles for % clay in Old Alluvium soils

## Things that can be hard to explain

- Interpretation of probability
- The role of prior distns  
(and noninformative prior distns)
- What is the right point estimate?
- How do we test hypotheses?
- Computational difficulties

## **Interpretation of probability**

- Most people have been (and continue to be) trained with the frequentist view of probability
- A common claim is that people relate more naturally to the “Bayesian” (subjective?) view, e.g., in confidence intervals
- This has not always been the case in my consulting/collaborative experiences
- The better-trained the person the more likely this is to be a problem

## The role of prior distributions

- Many want to use the likelihood function as a distn on parameters (e.g., Fisher's fiducial inference) but are unwilling to specify a prior distn
- This has always been the most problematic part for people
- Subjective prior distns often worry people
- The fact that the prior distn doesn't matter much for large sample size helps ....  
but not always true in hierarchical models
- In practice people are drawn to noninformative prior distns but ...
  - “noninformative” is not well defined
  - “flat” and “vague” are clear concepts but don't always yield noninformative prior distns
  - this subject is very confusing to people
- Recommendation might be to use vague proper prior distns and perform a sensitivity analysis

## Point estimates

- MLE is the dominant point estimation technique
- To get a unique Bayesian point estimate one must specify a loss function
- Example: animal breeding

Parameter	Posterior distribution			Poster.	REML
	2.5%	50%	97.5%	mean	
$\sigma_a^2$	757	6301	22919	7781	2253
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- REML estimates differ from posterior mean/median
- Why? ML is more like a mode

## Testing Hypotheses

- Applied science research is still often dominated by .05 significance level tests
- Can sometimes be addressed in a Bayesian analysis by examining 95% posterior interval (but not always, e.g., variance components)
- Bayes factors are an option
  - can be difficult to compute
  - sensitive to prior distns
  - interpretation?
- The best solution is to shift emphasis to point estimation and posterior intervals

### **Ex. 3: binary regr with random effects**

- Natural selection study
- 244 turtles in 31 families
- Response: survival (0/1)
- Predictors: birthweight, clutch/family effects
- Data collected by Janzen et al. (Ecology, 2000)
- It turns out that birthweight is a significant factor
- Question: are clutch effects important?

### Ex. 3: binary regr with random effects

- Probit model with random effects  
(Sinharay and Stern, 2000 technical report)
- Posterior inference
  - coefficient of birthweight
    - \* post. mean = .38, post. s. d. = .10
    - \* 95% int. = (.18, .59)
  - variance component ( $\sigma^2$ )
    - \* post. mean = .32, post. s. d. = .12
    - \* post. mode = .26
    - \* 95% int. = (.16, .61)
- Bayes factor (simple probit model vs probit with random effects): 3.25
- Bayes factor is sensitive to the prior on  $\sigma^2$
- Conclude variance parameter is not significant

## Summary/Conclusions

- Need to emphasize the difference between procedure development and procedure evaluation
- Outlook for increased use of Bayesian procedures is good
  - flexible inference
  - natural to develop/extend models (e.g., missing data)
  - success stories continue to develop
- Cautions
  - need to educate as we work
  - more work to be done on model checking/sensitivity analysis
  - these are generally not black-box procedures, we need to work with scientists