

A 2-dim rotational transformation. (linear)

$$\begin{aligned} Y_1 &= X_1 \cos \theta + X_2 \sin \theta & \theta \text{ constant} \\ Y_2 &= -X_1 \sin \theta + X_2 \cos \theta \end{aligned}$$

$$\underline{\hat{Y}} = C \underline{\hat{X}} \quad C = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}$$

means

$$\mu_{Y_1} = E[Y_1] = E[X_1 \cos \theta + X_2 \sin \theta].$$

$$= \mu_{X_1} \cos \theta + \mu_{X_2} \sin \theta. \quad \checkmark$$

$$\mu_{Y_2} = E[Y_2] = E[-X_1 \sin \theta + X_2 \cos \theta].$$

$$= -\mu_{X_1} \sin \theta + \mu_{X_2} \cos \theta. \quad \checkmark$$

covariance

$$\text{Cov}(Y_1, Y_2) = E[(Y_1 - \mu_{Y_1})(Y_2 - \mu_{Y_2})].$$

$$= E\left[\left((X_1 - \mu_{X_1}) \cos \theta + (X_2 - \mu_{X_2}) \sin \theta\right)\right.$$

$$\left. \cdot \left(- (X_1 - \mu_{X_1}) \sin \theta + (X_2 - \mu_{X_2}) \cos \theta\right)\right]$$

$$= (\sigma_{X_2}^2 - \sigma_{X_1}^2) \sin \theta \cos \theta$$

$$+ \sigma_{X_1 X_2} [\cos^2 \theta - \sin^2 \theta]$$

$$= (\sigma_{x_2}^2 - \sigma_{x_1}^2) \frac{1}{2} \sin(2\theta) + \sigma_{x_1 x_2} \cos(2\theta)$$

Recall: double angle formulas

$$\sin 2\theta = 2 \sin \theta \cos \theta$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

For the BVN to be independent, rotate  $(X_1, X_2)$  to  $(Y_1, Y_2)$  where  $\text{Cov}(Y_1, Y_2) = 0$ .

$$\text{note: } \sigma_{x_1 x_2} = \rho \sigma_{x_1} \sigma_{x_2}$$

$$0 = (\sigma_{x_2}^2 - \sigma_{x_1}^2) \frac{1}{2} \sin(2\theta) + \rho \sigma_{x_1} \sigma_{x_2} \cos(2\theta)$$

$$(\sigma_{x_2}^2 - \sigma_{x_1}^2) \frac{1}{2} \sin(2\theta) = \rho \sigma_{x_1} \sigma_{x_2} \cos(2\theta)$$

$$\tan(2\theta) = \frac{\sin(2\theta)}{\cos(2\theta)} = \frac{2\rho\sigma_{x_1}\sigma_{x_2}}{\sigma_{x_2}^2 - \sigma_{x_1}^2}$$

$$\theta = \frac{1}{2} \tan^{-1} \left( \frac{2\rho\sigma_{x_1}\sigma_{x_2}}{\sigma_{x_2}^2 - \sigma_{x_1}^2} \right)$$

$\theta$  is the angle of rotation to transform BVN to independence