Conditional Example

Particle Counter

A particle counter is imperfect and independently detects each incoming particle with probability p. If the distribution of the number of incoming particles in a unit of time is a Poisson distribution with parameter λ , what is the distribution of the number of counted particles?

Let N = # of incoming particles and X = # counted.

- 1. What is P(X = k | N = n) = ?
- 2. What is P(N = n)?
- 3. Compute P(X = k).

Is the conditional probability a regression?

```
### imperfect particle counter
lam = 10
p = 0.9
# probability distribution
len = 5
z = matrix(0,1+len,1+len)
for(i in 0:len){
       for(j in 0:i){
               z[1+j,1+i] = dbinom(j,size=i,prob=p)
       }
}
z
z.sum = apply(z, 2, sum)
z.sum
x.mean=0
for(i in 1:len){
       x.mean = c(x.mean,i*p)
}
x.mean
for(i in 0:len){
       X11()
       plot(z[,1+i],type="h")
}
# simulation, how to estimate p using linear regression through the
```

```
# origin
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B = 1000000

n = rpois(B,lam)

x = rbinom(n=B,size=n,prob=p)

plot(n,x,main="Counts detected vs Counts emitted, with E[X|N]")

x.fit = lm(x ~ 0+n)
summary(x.fit)
abline(x.fit)

Note that the estimated regression slope is very close to the true p